

# A strange recursion operator demystified

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## Abstract

We show that a new integrable two-component system of KdV type studied by Karasu (Kalkanlı) et al. (arXiv: [nlin.SI/0203036](#)) is bihamiltonian, and its recursion operator, which has a highly unusual structure of nonlocal terms, can be written as a ratio of two compatible Hamiltonian operators. Using this, we prove that the system in question possesses an infinite hierarchy of *local* commuting generalized symmetries and conserved quantities in involution, and the evolution systems corresponding to these symmetries are bihamiltonian as well.

Using the Panilevé test, Karasu (Kalkanlı) [1] and Sakovich [2] found a new integrable evolution system of KdV type,

$$\begin{aligned}u_t &= 4u_{xxx} - v_{xxx} - 12uu_x + vu_x + 2uv_x, \\v_t &= 9u_{xxx} - 2v_{xxx} - 12vu_x - 6uv_x + 4vv_x,\end{aligned}\tag{1}$$

and a zero curvature representation for it [2]. Notice that this system is, up to a linear transformation of  $u$  and  $v$ , equivalent to the system (16) from the Foursov's [3] list of two-component evolution systems of KdV type possessing (homogeneous) symmetries of order  $k$ ,  $4 \leq k \leq 9$ .

Karasu (Kalkanlı), Karasu and Sakovich [4] found that (1) has a recur-

sion operator of the form

$$\begin{aligned}
\mathfrak{R} &= \begin{pmatrix} R_{11} & R_{12} \\ R_{21} & R_{22} \end{pmatrix}, \\
R_{11} &= 3D_x^2 - 6u - 3u_x D_x^{-1}, \\
R_{12} &= \left[ -2D_x^5 + (2u + 3v) D_x^3 + (8v_x - 4u_x) D_x^2 \right. \\
&\quad \left. + (7v_{xx} - 6u_{xx} + 4u^2 - 6uv) D_x - 2u_{xxx} + 2v_{xxx} + 6uu_x - 3vv_x \right. \\
&\quad \left. - 4uv_x + u_x D_x^{-1} \circ v_x \right] \circ (3D_x^3 - 4v D_x - 2v_x)^{-1}, \\
R_{21} &= 6D_x^2 + 6u - 9v - 3v_x D_x^{-1}, \\
R_{22} &= \left[ -3D_x^5 + (12v - 18u) D_x^3 + (18v_x - 27u_x) D_x^2 + (14v_{xx} - 21u_{xx} \right. \\
&\quad \left. + 12u^2 + 12uv - 9v^2) D_x - 6u_{xxx} + 4v_{xxx} + 12uu_x + 6vv_x + 6uv_x \right. \\
&\quad \left. - 9vv_x + v_x D_x^{-1} \circ v_x \right] \circ (3D_x^3 - 4v D_x - 2v_x)^{-1}.
\end{aligned}$$

Here  $D_x$  is the operator of total  $x$ -derivative:  $D_x = \partial/\partial x + u_x \partial/\partial u + v_x \partial/\partial v + \sum_{j=2}^{\infty} (u_{jx} \partial/\partial u_{(j-1)x} + v_{jx} \partial/\partial v_{(j-1)x})$ , where  $u_{kx} = \partial^k u/\partial x^k$ ,  $v_{kx} = \partial^k v/\partial x^k$ , see e.g. [5] for further details. Let also  $\delta/\delta u = \partial/\partial u + \sum_{j=1}^{\infty} (-D_x)^j \partial/\partial u_{jx}$ ,  $\delta/\delta v = \partial/\partial v + \sum_{j=1}^{\infty} (-D_x)^j \partial/\partial v_{jx}$ ,  $\mathbf{u} = (u, v)^T$ , and  $\delta/\delta \mathbf{u} = (\delta/\delta u, \delta/\delta v)^T$ , cf. e.g. [5]. Here and below the superscript  $T$  denotes the matrix transposition. Recall that a function that depends on  $x, t, u, v$  and a *finite* number of  $u_{jx}$  and  $v_{kx}$  is said to be *local*, see e.g. [6, 5].

Because of the nonstandard structure of nonlocal terms in  $\mathfrak{R}$  the known ‘direct’ methods (see e.g. [7, 8, 9] and references therein) for proving the locality of symmetries generated by  $\mathfrak{R}$  are not applicable, so the question of whether (1) has an infinite hierarchy of local commuting symmetries remained open for a while. It was also unknown whether (1) is a bihamiltonian system.

We have [4]  $\mathfrak{R} = \mathfrak{M} \circ \mathfrak{N}^{-1}$ , where  $\mathfrak{M}$  and  $\mathfrak{N}$  are some (non-Hamiltonian) differential operators of order five and three. Inspired by this fact, we undertook a search of Hamiltonian operators of order three and five for (1), and it turned out that such operators do exist and the system (1) *is* bihamiltonian. Namely, the following assertion holds.

**Proposition 1** *The system (1) is bihamiltonian:*

$$\mathbf{u}_t = \mathfrak{P}_1 \delta H_0 / \delta \mathbf{u} = \mathfrak{P}_0 \delta H_1 / \delta \mathbf{u}, \quad (2)$$

where  $H_0 = -3u + v/2$ ,  $H_1 = 2u^2 - uv + v^2/9$ , and  $\mathfrak{P}_0$  and  $\mathfrak{P}_1$  are compatible Hamiltonian operators of the form

$$\mathfrak{P}_0 = \begin{pmatrix} D_x^3 - 2uD_x - u_x & 0 \\ 0 & -9D_x^3 + 12vD_x + 6v_x \end{pmatrix}, \mathfrak{P}_1 = \begin{pmatrix} P_{11} & P_{12} \\ P_{21} & P_{22} \end{pmatrix}, \quad (3)$$

where  $P_{11} = D_x^5 - 4uD_x^3 - 6u_xD_x^2 + 4(u^2 - u_{xx})D_x - u_{xxx} + 4uu_x - u_xD_x^{-1} \circ u_x$ ,  
 $P_{12} = 2D_x^5 - (2u + 3v)D_x^3 + 4(u_x - 2v_x)D_x^2 + (6u_{xx} - 7v_{xx} - 4u^2 + 6uv)D_x +$   
 $2u_{xxx} - 2v_{xxx} - 6uu_x + 3vu_x + 4uv_x - u_xD_x^{-1} \circ v_x$ ,  $P_{21} = 2D_x^5 - (2u + 3v)D_x^3 -$   
 $(10u_x + v_x)D_x^2 + (-4u^2 + 6uv - 8u_{xx})D_x - 2u_{xxx} - 2uu_x + 3vu_x + 2uv_x - v_xD_x^{-1} \circ$   
 $u_x$ ,  $P_{22} = 3D_x^5 + (18u - 12v)D_x^3 + (27u_x - 12v_x)D_x^2 + (21u_{xx} - 14v_{xx} - 12u^2 -$   
 $12uv + 9v^2)D_x + 6u_{xxx} - 4v_{xxx} - 12uu_x - 6vu_x - 6uv_x + 9vv_x - v_xD_x^{-1} \circ v_x$ .

Moreover, we have  $\mathfrak{R} = 3\mathfrak{P}_1 \circ \mathfrak{P}_0^{-1}$ , and hence  $\mathfrak{R}$  is hereditary.

Now we are ready to prove that (1) has infinitely many local commuting symmetries.

**Proposition 2** Define the quantities  $\mathbf{Q}_j$  and  $H_j$  recursively by the formula  $\mathbf{Q}_j = \mathfrak{P}_1 \delta H_j / \delta \mathbf{u} = \mathfrak{P}_0 \delta H_{j+1} / \delta \mathbf{u}$ ,  $j = 0, 1, 2, \dots$ , where  $H_0$ ,  $H_1$ ,  $\mathfrak{P}_0$  and  $\mathfrak{P}_1$  are given in Proposition 1. Then  $H_j$ ,  $j = 2, 3, \dots$ , are local functions that can be chosen to be independent of  $x$  and  $t$ , and  $\mathbf{Q}_j$  are local commuting generalized symmetries for (1) for all  $j = 1, 2, \dots$ .

Moreover, the evolution systems  $\mathbf{u}_{t_j} = \mathbf{Q}_j$  are bihamiltonian with respect to  $\mathfrak{P}_1$  and  $\mathfrak{P}_0$  by construction, and  $\mathcal{H}_j = \int H_j dx$  are in involution with respect to the Poisson brackets associated with  $\mathfrak{P}_0$  and  $\mathfrak{P}_1$  for all  $j = 0, 1, 2, \dots$ , so  $\mathcal{H}_j$  are common conserved quantities for all evolution systems  $\mathbf{u}_{t_k} = \mathbf{Q}_k$ ,  $k = 0, 1, 2, \dots$ .

*Proof.* Let us use induction on  $j$ . Assume that for  $\mathbf{Q}_j = \mathfrak{P}_1 \delta H_j / \delta \mathbf{u}$  there exist a local function  $H_{j+1}$  such that  $\mathbf{Q}_j = \mathfrak{P}_0 \delta H_{j+1} / \delta \mathbf{u}$  and  $\partial H_{j+1} / \partial x = \partial H_{j+1} / \partial t = 0$ , and let us show that then  $\mathbf{Q}_{j+1} = \mathfrak{P}_1 \delta H_{j+1} / \delta \mathbf{u}$  is local too and there exists a local function  $H_{j+2}$  such that  $\mathbf{Q}_{j+1} = \mathfrak{P}_0 \delta H_{j+2} / \delta \mathbf{u}$  and  $\partial H_{j+2} / \partial x = \partial H_{j+2} / \partial t = 0$ .

Since  $H_j$  is independent of  $x$ , we have

$$u_x \frac{\delta H_j}{\delta u} + v_x \frac{\delta H_j}{\delta v} = D_x \left( H_j - \sum_{j=1}^{\infty} \sum_{k=0}^{j-1} \left\{ u_{(j-k)x} (-D_x)^k \left( \frac{\partial H}{\partial u_{jx}} \right) + v_{(j-k)x} (-D_x)^k \left( \frac{\partial H}{\partial v_{jx}} \right) \right\} \right).$$

As  $H_j$  is local, the sum is actually finite, so  $D_x^{-1}(u_x \delta H_j / \delta u + v_x \delta H_j / \delta v)$  is a local expression, and thus  $\mathbf{Q}_{j+1} = \mathfrak{P}_1 \delta H_{j+1} / \delta \mathbf{u}$  is local too.

Next, as  $\mathbf{Q}_{j+1} = \mathfrak{P}_1 \delta H_{j+1} / \delta \mathbf{u}$ ,  $\mathbf{Q}_j = \mathfrak{P}_0 \delta H_{j+1} / \delta \mathbf{u}$ , and  $\mathfrak{R} = 3\mathfrak{P}_1 \circ \mathfrak{P}_0^{-1}$ , we can (formally) write  $\mathbf{Q}_{j+1} = (1/3)\mathfrak{R}\mathbf{Q}_j$ , cf. e.g. Section 7.3 of [5]. As  $\mathfrak{R}$  is a recursion operator for (1), its Lie derivative along  $\mathbf{Q}_0$  vanishes:  $L_{\mathbf{Q}_0}(\mathfrak{R}) = 0$ . By Proposition 1  $\mathfrak{R}$  is hereditary, so we have [10]  $L_{\mathbf{Q}_{j+1}}(\mathfrak{R}) =$

$(1/3)^{j+1}L_{\mathfrak{P}^{j+1}\mathcal{Q}_0}(\mathfrak{R}) = 0$ , whence  $L_{\mathcal{Q}_{j+1}}(\mathfrak{P}_0) = 3L_{\mathcal{Q}_{j+1}}(\mathfrak{R}^{-1} \circ \mathfrak{P}_1) = 3\mathfrak{R}^{-1} \circ L_{\mathcal{Q}_{j+1}}(\mathfrak{P}_1) = 3\mathfrak{R}^{-1} \circ L_{\mathfrak{P}_1\delta H_{j+1}/\delta \mathbf{u}}(\mathfrak{P}_1) = 0$ , cf. e.g. [11, 12].

In turn,  $L_{\mathcal{Q}_{j+1}}(\mathfrak{P}_0) = 0$  implies that there exists a local function  $H_{j+2}$  such that  $\mathcal{Q}_{j+1} = \mathfrak{P}_0\delta H_{j+2}/\delta \mathbf{u}$ . The proof of this fact goes along the same lines as it was done in [13] for the second Hamiltonian structure of the KdV equation. Finally, as the coefficients of  $\mathfrak{P}_0$  and  $\mathfrak{P}_1$  are independent of  $x$  and  $t$ , it is immediate that we always can choose  $H_{j+2}$  so that it is independent of  $x$  and  $t$ .

The induction on  $j$  starting from  $j = 0$  and the use of Theorem 7.24 of Olver [5] complete the proof.  $\square$

In order to handle properly the nonlocal terms, for any local  $H$  such that  $\partial H/\partial x = 0$  we shall set, in agreement with the above (see e.g. [17]–[20] for more details on dealing with nonlocalities),

$$D_x^{-1} \left( u_x \frac{\delta H_j}{\delta u} + v_x \frac{\delta H_j}{\delta v} \right) = H_j - \sum_{j=1}^{\infty} \sum_{k=0}^{j-1} \left\{ u_{(j-k)x} (-D_x)^k \left( \frac{\partial H}{\partial u_{jx}} \right) + v_{(j-k)x} (-D_x)^k \left( \frac{\partial H}{\partial v_{jx}} \right) \right\}.$$

Then, for instance, the first commuting flow for (1) is

$$\begin{aligned} u_{t_1} &= 2u_{5x} - (5/9)v_{5x} - 20uu_{xxx} + (50/9)uv_{xxx} + (40/9)vu_{xxx} \\ &\quad - (10/9)vv_{xxx} - 50u_x u_{xx} + (125/9)u_x v_{xx} + (40/3)v_x u_{xx} - (10/3)v_x v_{xx} \\ &\quad - (40/3)vuu_x + (20/9)vuv_x + 40u^2 u_x - (80/9)u^2 v_x + (5/9)v^2 u_x, \\ v_{t_1} &= 5u_{5x} - (4/3)v_{5x} - 40uu_{xxx} + 10uv_{xxx} + (10/3)vu_{xxx} - (5/9)vv_{xxx} \\ &\quad - 120u_x u_{xx} + 30u_x v_{xx} + (80/3)v_x u_{xx} - (55/9)v_x v_{xx} + (160/3)vuu_x \\ &\quad - 20vuv_x + (40/3)u^2 v_x - (40/3)v^2 u_x + (35/9)v^2 v_x. \end{aligned}$$

By Proposition 2 this system is bihamiltonian, and indeed we can write it as

$$u_{t_1} = \mathfrak{P}_1 \delta H_1 / \delta \mathbf{u} = \mathfrak{P}_0 \delta H_2 / \delta \mathbf{u},$$

where

$$H_2 = \frac{7}{162}v^3 - \frac{8}{3}u^3 - \frac{5}{9}v^2u + \frac{20}{9}u^2v - u_x^2 + \frac{5}{9}v_x u_x - \frac{2}{27}v_x^2.$$

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